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Type 2160A...

# NC Joining Module NCFB

## with Cost Optimized Standard Design

The joining module Type 2160A... (in two size available) with integral piezoelectric force sensor and measuring ranges of 5 ... 50 kN is for force-displacement assembly and joining processes. This extremely economically priced NC joining module NCFB allows the user to implement standard joining processes cost-effectively using electromechanical joining modules.

- Force feedback control
- Direction of measurement: compression
- · Integral charge amplifier
- High measuring accuracy in two ranges
- High rigidity
- · High level of sensor overload protection

## Description

The NC joining module Type 2160A... consists of a robust case with integral piezoelectric force sensor. Its motor has an absolute encoder for exact positioning. The compression forces acting on the sensor's piezoelectric measuring element generate a proportional electric charge converted by the integral charge amplifier into an analog voltage signal.

The motor of the NC joining module is an electronically commutated AC servo type controlled by a servo electronics to ensure constant rotational and therefore translational speed. Standard functions such as block pressing, position pressing and force feedback controlled pressing as well as intermediate positioning are supported.

The NC joining module NCFB can be operated with the IndraDrive servo amplifier in combination with maXYmos NC type 5847A... The communication between IndraDrive and maXYmos NC takes place in real-time via SERCOS III. Several field bus slave interfaces are available onboard for customer controlling. PROFIBUS, PROFINET, EtherNet/IP or even EtherCAT can be used with the maXYmos NC can be used at the customer's choosing. Quality data can be transmitted via the Ethernet interface through different protocols and a visualization via VNC® or a data backup can be performed.



## **Application**

The NC joining module NCFB Type 2160A... is ideal for use in automated production systems.

Assembly is possible vertically and horizontally. The module can be flanged onto the frame of the production unit. Threaded bores of sufficient strength to hold tools are provided in the ram of the threaded spindle drive (Figure 1 and 2).



#### Technical Data

Dimensions	mm	Fig. 1 and 2	
Assembly options		flange assembly	
Weight			
Type 2160A15	kg	35	
Type 2160A50	kg	145	
Max. tool weight Type 2160A15			
without holding brake1)	kg	10	
with holding brake <sup>1)</sup>	kg	50	
Max. tool weight Type 2160A50			
without holding brake1)	kg	15	
with holding brake <sup>1)</sup>	kg	100	
Holding brake	V/A	24/0,7	
Direction of measurement		compression	
Measuring range			
Type 2160A15	kN	5, 15	
Type 2160A50	kN	25, 50	
Length of stroke			
Type 2160A15	mm	200	
Type 2160A50	mm	400	
Practical repeatability	mm	0,01	
Tool holder	mm	Fig. 1 and 2	
Max. movement speed			
Type 2160A15	mm/s	250	
Type 2160A50	mm/s	150	
Displacement sensor system		absolute encoder	
Resolution	mm	0,001	
Force sensor		piezoelectric	
Temperature range	°C	10 40	

Protection class		IP54		
Linearity in all ranges	%FSO	≤1		
Accuracy class force sensor	%	0,5		
Service life of spindle				
(acc. to defined drive profile)	cycles	approx, 5 million		
Short stroke				
Type 2160A15	mm	≤70		
Type 2160A50	mm	≤120		
Lubrication connection	ction standard-			
(internal)		lubrication nipple		
Servo amplifier <sup>2)</sup>	Bosch-Re	Bosch-Rexroth Type 2180A		
Standard interface	SERC	SERCOS III (internal bus)		
Evaluation unit <sup>3)</sup>	maXYm	maXYmos NC Type 5847A		
Standard interface	PR	PROFIBUS, PROFINET,		
	Et	EtherNet/IP, EtherCAT		
Power supply	VDC	24 ±5 %		

A bending of the plunger depending on the tool weight must be considered for a horizontal installation.

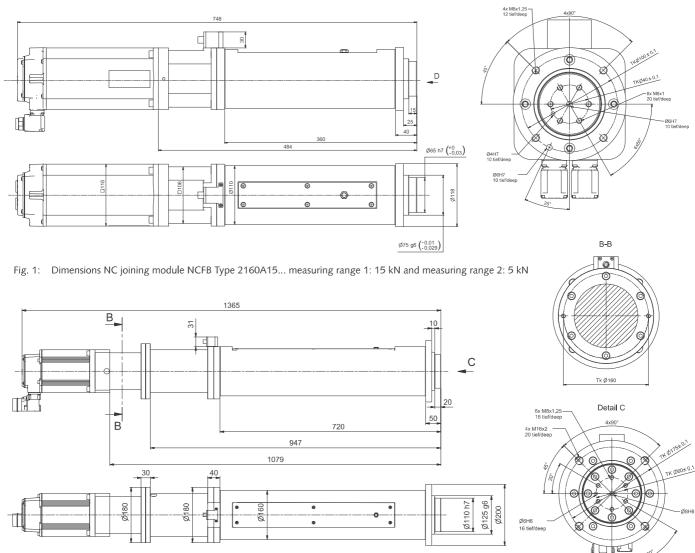
<sup>&</sup>lt;sup>1)</sup> Attention has to be paid to possible radial forces independent of the installation position. Permissible tool weight may have to be reduced for manual feed.

 $<sup>^{\</sup>mbox{\tiny 2)}}$  Servo amplifier see accessories data sheet 003-125 Type 2180A...

 $<sup>^{\</sup>scriptscriptstyle{(3)}}$  Evaluation unit maXYmos NC Type 5847A... see data sheet 003-126



## Dimensions NC Joining Module NCFB Type 2160A...



The radial forces (for example due to the weight of the tool) must be considered for the installation. An external guide may have to be provided for the plunger.

Fig. 2: Dimensions NC joining module NCFB Type 2160A50... measuring range 1: 50 kN and measuring range 2:25 kN



Type/Art. No.

## Functional Principle with maXYmos NC Type 5847A...

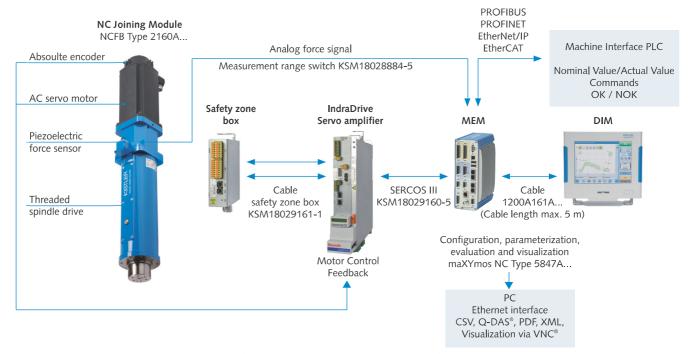


Fig. 3: Functional principle of NC joining system with NC joining module NCFB Type 2160A... and maXYmos NC Type 5847A...

## **Included Accessories**

None

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Optional Accessories	Type/Art. No.	<ul> <li>NCFB 15 motor cable, length 5 m RKL4302</li> </ul>	KSM341600-5
• Evaluation unit maXYmos NC <sup>4)</sup> (MEM)	5847A	<ul> <li>NCFB 50 motor cable,</li> </ul>	
Bearing rail adapter for 35 mm		length 5 m RKL4306	KSM347990-5
Cap rail including 2 fastening		<ul> <li>NCFB MSK Feedback cable,</li> </ul>	
screws M3x10	5700A31	length 5 m RKG4200	KSM303500-5
• Display module (DIM) with pedestal	5877AZ000	<ul> <li>maXYmos Force transmitter cable,</li> </ul>	
<ul> <li>Connection cable maXYmos</li> </ul>		length 5 m	KSM18028884-5
MEM on DIM, length 5 m	1200A161A5	<ul> <li>SERCOS III connection cable,</li> </ul>	
Servo amplifier <sup>2)</sup>	2180A	length 5 m	KSM18029160-5
		<ul> <li>Safety zone box cable,</li> </ul>	
3) -		2 cables required), length 1 m	KSM18029161-1

Cable

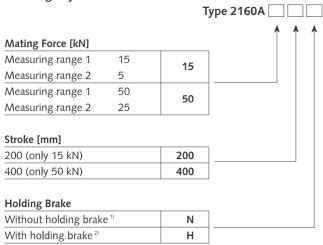
Other length on request.

 $<sup>^{\</sup>mbox{\tiny 2)}}$  Servo amplifier Type 2180A... see accessory data sheet 003-125

<sup>&</sup>lt;sup>4)</sup> Evaluation unit maXYmos NC Type 5847A... see data sheet 003-1266



#### **Ordering Key**



#### Note:

<sup>1)</sup> Without holding brake 10 kg at 15 kN

15 kg at 50 kN

<sup>2)</sup> With holding brake 50 kg at 15 kN

100 kg at 50 kN

## **Ordering Example**

Type 2160A50400N

NC joining module NCFB **Type 2160A...**, measuring range 1: **50 kN**, stroke: **400** mm, without holding brake: **N.** 

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